

# NAVIGATION AND ROBOTICS IN TOTAL JOINT AND SPINE SURGERY%0A

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Orthopaedic surgery is urr c ently just a few moments past the sunrise of computer implementation for the per formance of surgery itself. OUT pe s cially has always seemed to have a nearly unique. over arching characteristic -it deals almost exclusively with alteration, typically rebuilding or <http://chrismillerworks.co/Navigation-and-Robotics-in-Total-Joint-and-Spine-Surgery--.pdf>

## **Navigation and Robotics in Total Joint and Spine Surgery**

Because of its simplicity, computer navigation will be an early tool in such areas as total joint replacement, anterior cruciate ligament reconstruction, and placement of pedicle screws in complex spinal surgery. New techniques in Minimally Invasive Surgery will require the precision and digital "surgical exposure" offered by the computer. However, we anticipate in a few years, that robotics <http://chrismillerworks.co/Navigation-and-Robotics-in-Total-Joint-and-Spine-Surgery--.pdf>

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### **Navigation and Robotics in Spinal Surgery Where Are We**

In light of these characteristics, spine surgery may actually be an ideal candidate for the integration of navigation and robotic-assisted procedures. With this paper, we aim to critically

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### **Navigation and Robotics in Spinal Surgery Where Are We**

Spine surgery has experienced much technological innovation over the past several decades. The field has seen advancements in operative techniques, implants and biologics, and equipment such as computer-assisted navigation (CAN) and surgical robotics.

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