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Interdisciplinary Applications of Kinematics Proceedings

This book collects a number of important contributions presented during the Second Conference on Interdisciplinary Applications of Kinematics (IAK 2013) held in Lima, Peru.

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Kinematics is an exciting area of computational mechanics and plays a central role in a great variety of fields and industrial applications nowadays. Apart from research in pure kinematics, the field deals with problems of practical relevance that need to be solved in an interdisciplinary manner in order for new technologies to develop.

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Kinematic Modelling and Analysis of a 5 Axis Articulated

In physical applications, it is important to describe the position of the end effectors of the robot manipulator in global coordinates. In transforming, the coordinates of the end effectors from the local position to the global position, the robot movements are represented by a series of movements of rigid links. Each link defines a proper transformation matrix relating the position of the

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Mechatronic Design of a Lower Limb Exoskeleton IntechOpen

The applications of exoskeleton robots are varied, ranging from military applications to the medical field. In the medical field, exoskeletons in conjunction with rehabilitation therapies can assist patients with spinal cord injury, stroke and lower limb paralysis, caused by hemiplegia, to perform gait training [4].

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Kinematics in 1 D Harvard University

KINEMATICS IN 1-D 2.5. Two cars, with initial speeds of $2v$ and v , lock their brakes and skid to a stop. Assume that the deceleration while skidding is independent of the speed. The ratio of the distances traveled is (a) 1 (b) 2 (c) 4 (d) 8 (e) 16 2.6. You start from rest and accelerate with a given constant acceleration for a given distance. If you repeat the process with twice the

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