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Published by Elsevier B.V. Peer-review under responsibility of the scientific committee of the International Conference on Computational Science This space is reserved for the Procedia header, do not use it Exploiting Hybrid Parallelism in the Kinematic Analysis of Multibody Systems Based on Group Equations Gregorio Bernabe 1, Jose -Carlos Cano2, Javier Cuenca1, Antonio Flores1, Domingo

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Computer aided kinematics and dynamics of mechanical

tional and recent computational methods are com- pared, leading to the objectives and possibilities of modern computational simulation techniques, Chapter 2 gives an introduction to various mathematical definitions and results for vector and matrix algebra manipulations. Important topics

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Kinematical analysis of overconstrained and

Abstract. We investigate and explain several exceptional phenomena appearing in mechanism kinematics. The starting point for the kinematical analysis of a mechanism is the formation of the relevant constraint map defining the constraint equations for the coordinates of the particular system.

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